

Computer Engineering and Mechatronics MMME3085

Dr Louise Brown

Pointers recap (1)

Address Memory

char Data = $10;$

We have no control over where the system stores this

Pointers recap (2)

Address Memory

No value assigned to this pointer at the moment It could contain any random data

Pointers recap (3)

Address Memory

char Data = ; χ char *pData = NULL;

This is much safer!

Pointers recap (4)

Address Memory

char Data = ; char $*$ pData = NULL; D _{Data} D **pData** = $\&$ **Data**; Use & to get the address of a variable

Pointers recap (5)

Address Memory

char Data = 10 ; char $*$ pData = NULL; pData = &Data; $*$ pData = 20; **Pointer** dereferencing using

*

or 'what pData is pointing $at' = 20$

Pointers recap (6)

Address Memory

char Data = 10 ; char $*$ pData = NULL; pData = &Data; $*$ pData = 20; char $i = *pData;$

i = 'What pData is pointing at'

Introduction

▪Today we will cover:

- Chapter 16 Dynamic memory allocation
- ▪Chapter 17 Function programming (part 3)
- ▪Chapter 19 Advanced data types in C

Start recording!!

Chapter 16

Dynamic Memory Allocation

Say we need an array of Floats

- Do we know how big it will be ?
- ▪Do we go for a 'largest possible' solution ?

NO !

- We waste memory
- ▪Our code may crash as our 'guess' may be too small
- Passing the data in functions becomes time consuming

Use a pointer and dynamically create the array as:

- We can ensure we have enough memory free
- We get exactly the right size array
- We can free the memory up when it is finished with
- We can pass all the data to analysis routines in one go
- We can even save all the data to file in one go!

Basically, we are writing good, robust, memory efficient code!

Pointers: in practice (1)

There are four 'steps' in using a pointer when using it to allocate an array

- Create the pointer
- Assign it a valid address in memory
- Use the memory associated with the pointer
- **Free up the memory**

There is the 4th step when using pointers with arrays (mentioned earlier!).

Create the pointer

- This is done the same as if we were declaring a pointer for a single variable
- If must be of the type we wish our array to be e.g.
	- int $*$ a; $\frac{1}{2}$ For an array of integers

float *XData; // For an array of floats

Allocate the pointer…

This is where the process differs.

- Previously we assigned the address of *an existing variable* to a pointer
- Now, we wish to ask for a base memory address where we can start to store values

There are two functions we can use for this

malloc

calloc

They are almost identical, often it is a mix of personal preference/code requirements that will determine which is used

Allocates a block of memory (given in bytes) **but does not initialise it**

```
void *malloc(size_t size);
```
Prototype in alloc.h and stdlib.h

Inputs:

• Size in bytes of memory requested to be allocated

Returns:

- a pointer to the Newly allocated block, or
- **NULL** if not enough space exists for the new block.

Note: If size == 0, it returns **NULL**.

Allocates space for n items of size bytes each and **initialises each item to zero**

void *calloc(size t nitems, size t size);

Prototypes in stdlib.h and alloc.h

Inputs:

- nitems: number of items to allocate memory for
- size: size, in bytes, of each item

Returns

- a pointer to the newly allocated block or
- **NULL** if not enough space exists.

Frees blocks allocated with

- malloc or
- calloc

Prototype is void free (void *block);

Found in stdlib.h & alloc.h

Note:

• We must use this to return memory, it is NOT automatically done when a function exits (only the pointer is released)

An Example (or 3)

We will create dynamically an integer array of size 'n'

- \blacksquare Fill it with the values $0 \ldots n$
- ▪Display the values (backwards)

Free up the memory used

LC16\dynamic_1.c, LC16\dynamic_2.c, LC16\dynamic_3.c,

Just as we can allocate memory for a 1D array, we can do the same for 2D, 3D.. arrays.

- **If is however somewhat complex**
	- **If involves creating arrays of pointers**
	- **Even more asterisks**
- As such, we will not cover it now

Chapter 17

Function Programming (Part 3)

Passing arrays to functions (1)

$In...$

- •Chapter 15: We saw how we can use a pointer to access items of an existing array
- •Chapter 16: We developed the skills to allocate memory for an array (obtaining the base address to use)

Now

• Let us combine this with the knowledge on passing pointers to functions (Chapter 14)

We can pass an entire array to a function simply by passing its address

 \blacksquare In fact, this is what C does for us \odot (try and stop it!).

In the function call, we just provide the array variable,

■ e.g. if we had declared an array as int MyArray [1000];

Our function call would be of the form

```
MyFunction ( MyArray );
```
Note: we could use: MyFunction ($\&MyArray[0]$) if we really wanted to!

When defining the function, we need to declare the parameter appropriately

Assuming we are passing an array of integers, the 'easiest' (and most obvious when reading code) is to declare the parameter as

int ArrayToReceive[] (the [] indicates an array without 'fixing' the size) void MyFunction(int ArrayToReceive[]);

We could of course treat it as a pointer as it will be being passed a memory address, e.g.

```
void MyFunction( int *ArrayToReceive );
                                            Does the same thing but not so 
                                            obvious that it's expecting an array
```


In the function we access the array (using any of the methods from chapter 15), e.g.

ArrayToReceive[n]

```
*(ArrayToReceive+n)
```
Note:

- As a pointer has been passed, the **original** array is accessed
- **NOT A COPY**
- i.e. you can (say) populate an array in a function
- The function does not know how big the array is! (Be careful!)

Using arrays passed to functions (2)

We Will create an integer array of size 'n'

- Pass the array to a function (very efficiently!)
- Populate the array
- Pass the array to another function
- Display a result

Then repeat with a dynamically allocated array.

In this case we must free up the memory used at the end

Chapter 19

Advanced Data Types in C - Structures

Collections of variables stored under one name

Usually a set of related information

e.g. Name and address Material properties A set of coordinates

Defining a Structure (1)

```
struct Struct_Name
   \{variable definitions
  };
keyword structure tag
```


Defining a Structure (2)

structure type (used for variable declaration)

```
struct Struct_Name
\big\{variable definitions
};
```


Defining a Structure (3)

structure type (used for variable declaration)

```
struct Struct Name
{
  variable definitions
};
          Variables contained 
          in structure
```
Enclose variables in brackets and don't forget the semicolon!

structure type (used for variable declaration)

```
struct Struct_Name
{
  variable definitions
};
          Variables contained 
          in structure
```
Enclose variables in brackets and don't forget the semicolon!

```
eg: struct Employee
     {
       int id, phone;
       char Surname[40];
       char Initials[5];
     };
```


You can have any variable type within the structure definition

```
eg: struct Employee
     {
       int id, phone;
       char Surname[40];
       char Initials[5];
       float Salary[12];
       int Matrix[10][20];
       int *LookUp;
     };
```


Using your Structure : Part 1

To declare a variable using the type of structure defined use the structure type specified (the keyword plus the tag)

struct Employee JoeBlogs;

For an array of structures:

struct Employee Employees[10];

For a pointer to a structure:

struct Employee *Employee1;

Use the 'dot operator' to access individual structure variables:

StructureName.Element_Name

For example:

- Name = Employees.Surname;
- $Wage = Employees.Salary[0];$

Individual Structures of the same type can be set equal to each other

```
eg.
    MyData[0] = MyData[4];But not
    NewData = MyData;
```
LC19\structure_1.c , LC19\structure_2.c , LC19\structure_3.c

Structures can be passed to functions as a parameter **MyFunc(employee1)**

Where the function declaration would be **MyFunc(struct Employee employee)**

Structure pointers

To change the data in the structure from within the function, pass a pointer **MyFunc(&employee)** Then the function declaration would be **MyFunc(struct Employee *employee)**

Members of a structure can be accessed via the pointer using -> **employee->Surname = "Smith"** Or **(*employee).Surname = "Smith"**

which allow members of a structure in the calling function to be accessed

LC19\StructureFunc.c

Chapter 19

Advanced Data Types in C – Enums, Const, Unions, #define and Advanced Structures

- When developing code, we aim to make it as readable and maintainable as possible.
- One way is to define text labels (e.g. M_PI) that we can use in our code
- We do this using the compiler directive #define, e.g. #define UP 1 #define DOWN 2

Make sure you don't put a semicolon at the end of the line – it will create problems when the compiler does the 'find and replace'

When we compile our code, the compiler does an initial 'find and replace' of these so (assuming #define UP 1) so,

$$
if (i == UP)
$$
 // easier for us to read

Becomes

if $(i == 1)$ // What is actually compiled

#define: A clever trick

```
#define Size 50
main()
{
    int Array[Size][Size];
    int iCols = Size;
    int iRows = Size;
```
While we do have to recompile code, this allows us to change the size of an array to match a problem.

If we use 'Size' in loops etc. we know too we will stay inside the array bounds.

This is also a good way for changing parameters within an application (e.g. you might #define a value for resistivity or permittivity which is then used in equations).

#define: A word of caution (1)

These need to be used with caution, one thing to note is **DO NOT** put a semicolon on the end of a #define e.g.

```
#define UP 1;
```
As

```
if ( i == UP ) // easier for us to read
```
Becomes

if ($i == 1$;) // What is actually going to be compiled

Which is an error and does not compile!

As this is a simple 'find and replace' the compiler cannot spot the following problem (and is very hard for us to track down as it is not an 'error').

```
#define UP 1 
#define DOWN 1
if ( i == UP )\{// some code for 'UP'
}
if ( i == DOWN )
\{// some code for DOWN
}
                                      #define UP 1 
                                      #define DOWN 1
                                      if ( i == 1 )
                                       {
                                         // some code for 'UP'
                                      }
                                      if ( i == 1 ){
                                         // some code for DOWN
                                      }
       Written as Compiled as
```


Enumerated Types

This is a simple way of defining an integer type and setting unique, incrementing values to them (in one go!)

enum Enum Name { types }

Eg

enum Days { mon, tue, wed, thu, fri } ;

It also has the advantage that the numbers NEVER replicate $-$ so avoiding the previous problem.

By default, enum's start at zero

```
enum Days { mon, tue, wed, thu, fri }
So mon = 0, tue = 1 etc
```
But we can define a start value

enum Days $\{$ mon=1, tue, wed, thu, fri $\}$ So mon $= 1$, tue $= 2$ etc

C19\enum.c TestEncoder

A static variable is one that when defined in a function is not destroyed when the function terminates.

It holds the value and can be accessed the next time the function is called.

Often used to count the number of times a function is called.

C19\static.c

const is a keyword used to make the value of an identifier constant. **const int X = 30;**

Unlike #define, **const** is scope controlled

A const variable will have memory space allocated to it (but this may be device/compiler dependent)

[https://www.baldengineer.com/const-vs-define-when-do-you-them](https://www.baldengineer.com/const-vs-define-when-do-you-them-and-why.html)[and-why.html](https://www.baldengineer.com/const-vs-define-when-do-you-them-and-why.html)

LC19\ConstHashDefine.c

A union is a set of variables that

- Overlap
- Start at the same place in memory
- They are defined in a similar fashion to structures
- **They can be used to save memory**

Unions – a graphical explanation

The storage for each variable overlaps – in this case the char array is defined to cover the whole range of bytes of memory used.

Note: sizes in bytes will be machine dependent

MotorControlSkeleton.ino

Advanced Structures

A C struct can have bit fields

 \blacksquare append a \blacksquare and a number to an integer type

```
struct SmallNumbers
{ 
  unsigned int a:4; 
  unsigned int b:4; 
  unsigned int c:4; 
  unsigned int d:4; 
};
```


Bit Fields

```
struct SmallNumbers
{ 
  unsigned int a:4; 
  unsigned int b:4; 
  unsigned int c:4; 
  unsigned int d:4; 
};
```
struct SmallNumbers has 4 members

- Each member has 4 bits
- The value each can take is defined by the number of bits
- The structure is automatically made the correct size
- Structure parts are independent of each other

Another example of bitfields

```
struct Bits
```

```
{
  unsigned char b0 : 1;
  unsigned char b1 : 1;
  unsigned char b2 : 1;
  unsigned char b3 : 1;
  unsigned char b4 : 1;
  unsigned char b5 : 1;
  unsigned char b6 : 1;
   unsigned char b7 : 1;
};
```
Assigning: struct Bits cByte = $\{0,1,1,0,1,1,1,1\}$;

Or $cByte.b0 = 0;$ $cByte.b1 = 1;$

We can also leave gaps

Register settings, e.g.

- Many devices use a single register to set a series of values
- We could set/reset each bit but this would be very tedious
- Better to set a structure and the we can control each bit without affecting other bits

Eg. - a typical engineering case (1)

Serial port control register

BR3 BR2 BR1 DB2 DB1 SB2 SB1 P

- P: Parity $(0=odd, 1=even)$
- SB: Stop bits (0 bits,1 bit or 2 bits)
- DB: Data bits $(0=6 \text{ bits}, 1=7 \text{ bits}, 2=8 \text{ bit})$
- BR: Baudrate ([x+1] * 1200), x= 0..7

Eg. - a typical engineering case (2)

Serial port control register

BR3 | BR2 | BR1 | DB2 | DB1 | SB2 | SB1 | P

P: Parity $(0=odd, 1=even)$ DB: Data bits $(0=6 \text{ bits}, 1=7 \text{ bits}, 2=8 \text{ bit})$ SB: Stop bits (0=0 bits, 1=1 bit, 2=2 bits) BR: Baudrate ([x+1] * 1200), x= 0..7

To configure the port we would put zeros and ones in the relevant boxes and work out the decimal (or hex) value and assign this to the register e.g. for 9600,8,1,E

A bit field struct can help make this more manageable as we can separate items struct RS232

```
{
  unsigned char p : 1; // parity bit
  unsigned char sb : 2; // stop bits
  unsigned char db : 2; // data bits
  unsigned char baud : 3; //baud rate
};
```
Assigning:

```
struct RS232 serial = \{1, 1, 2, 7\};
```
Or

```
serial.p = 1;
serial.sb = 1;
serial.db = 2;serial.load = 7;
```


Improving even further…

Note: For REALLY good code we can use #define to create constants for the various parameters and use these in our code.

This makes it very easy to read and to update, consider our previous example…

Which is much easier to read

Giving

```
Assigning: 
       struct RS232 serial = {parity_odd, stop_bits_1 , data_bits_2, BAUD_9600};
   Or 
      serial.p = parity_odd; 
      serial.sb = stop_bits_1;
       serial.db = data bits_2;serial.baud = BAUD 9600;
Instead of
   Assigning: 
       struct RS232 serial = \{1, 1, 2, 7\};
   Or 
      serial.p = 1;
      serial.sb = 1; etc.
```